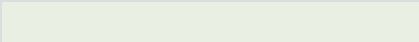


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- ▶ Micromachined Gyroscope Design Allowing for Both Robust Wide-Bandwidth and Precision Mode-Matched Operation
- ▶ 3-D Folded MEMS Technology For Multi-Axis Sensor Systems
- ▶ Prioritizable IMU Array (Prio-IMU) for Enhanced Pedestrian Navigation
- ▶ Micro-glassblowing for Gyroscope Fabrication

