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Long Baseline Acoustic Navigation Of Deeptowed And Autonomous Underwater Vehicles

Tech ID: 19927 / UC Case 2005-086-0

TECHNOLOGY DESCRIPTION

UC San Diego inventors have devised a novel method for locating one or more deeptowed or autonomous underwater vehicles during

geophysical or oceanographic surveys. The invention has the following features:

- Works in real time.
- Saves the time and cost of deploying, navigating, and recovering the seafloor transponder net.
- ▶ Has the navigation array move with the underwater vehicle, rather than remaining stationary.

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OTHER INFORMATION

KEYWORDS

LBL, underwater positioning

CATEGORIZED AS

► Transportation

Other

Engineering

Other

RELATED CASES

2005-086-0

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